Utilization of Big Data in Motor Drive System base on Model Predictive Control モデル予測制御に基づくモータ駆動システムにおけるビッグデータの活用

名古屋大学 実世界データ循環学リーダー人材養成プログラム 嶋岡 雅浩 (Masahiro Shimaoka) Nagoya University Graduate Program for Real-World Data Circulation Leaders 工学研究科 情報・通信工学専攻 / D1

Control Technology \times Data Circulation

My Viewpoint

Utilizing Big Data for Control Algorithm

Content of steady in Program

I have studied

- How to focus attention on the data
- How to handle the data through Real-World Data Circulation

Contribution fields of control technology

- Control technology supports many fields and products
- The multiplication of Control Technology and Data Circulation will create New Value from now on

Problem of MPC

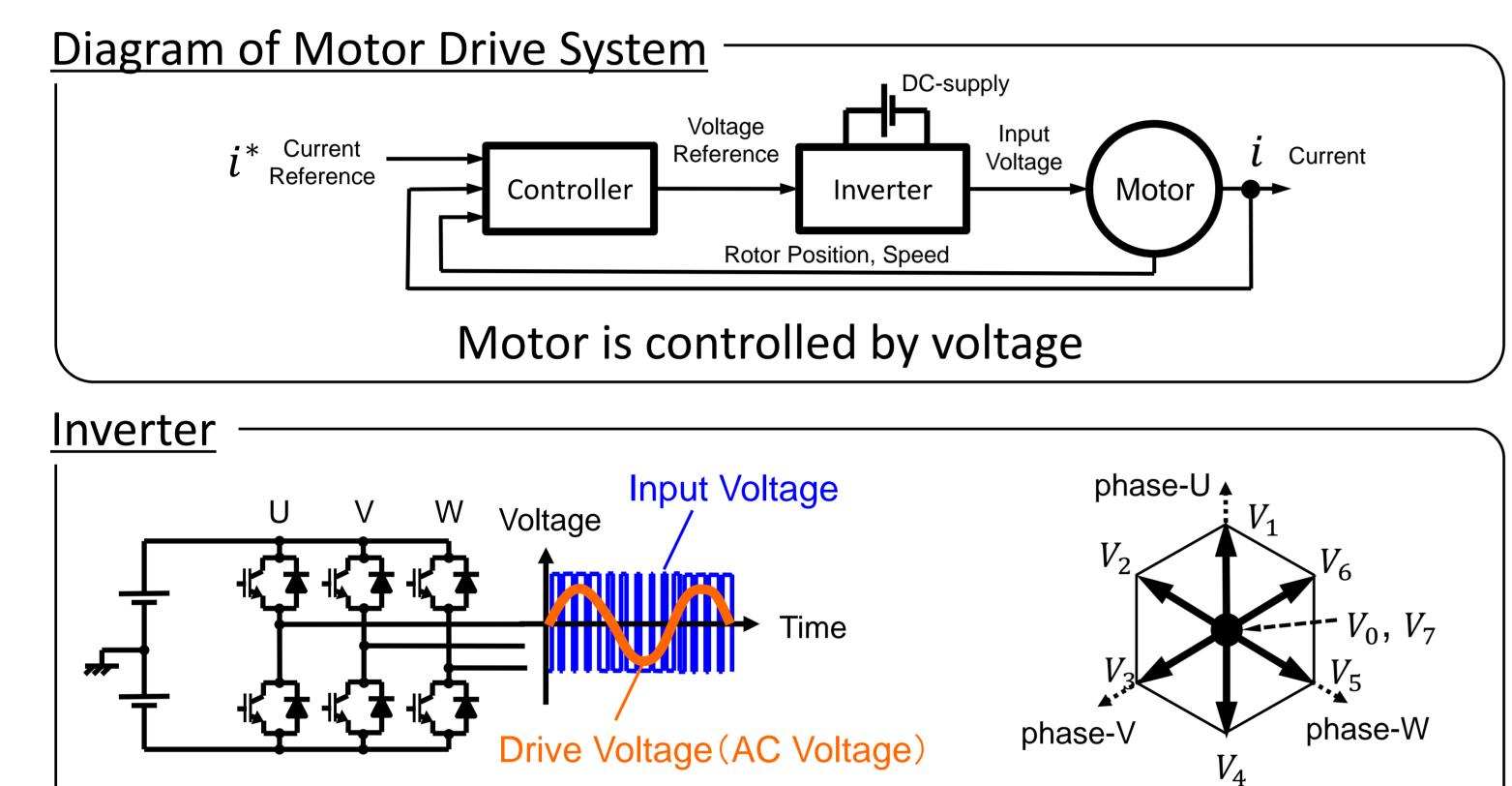
My research topic

The application of **Model Predictive Control(MPC)** for Motor Drive System

Motor Drive System

Important factors supporting the Modern life

ex) Consumer Electronics, Electric Vehicle and etc.



Calculation amount of prediction is very huge

Number of Combinations is over thousands

Prediction and evaluation time > control period(tens micro seconds)

Implementation of MPC is impossible

MPC needs to reduce calculation time for realization

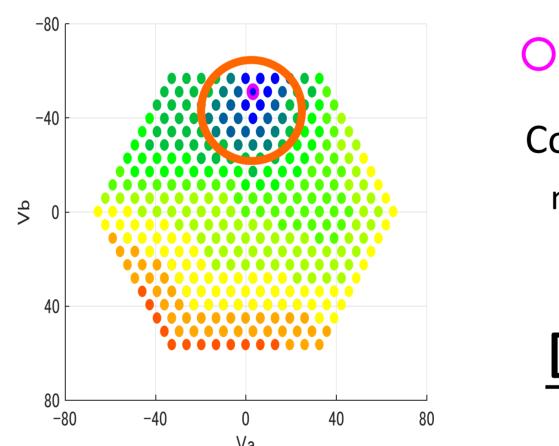
I have been focusing on data utilization for reducing the calculation time of MPC

Data Utilization in MPC

The cost function distribution in voltage vector space

I paid attention to the relationship of

cost function value and voltage of each combination



○ : minimum value

Color Scale of Cost Function value



Inverter converts DC-supply to AC voltage

How to decide Input Voltage

Conventional method

Controller calculates amplitude of drive voltage(v_{amp}) from the error between reference and sampled current

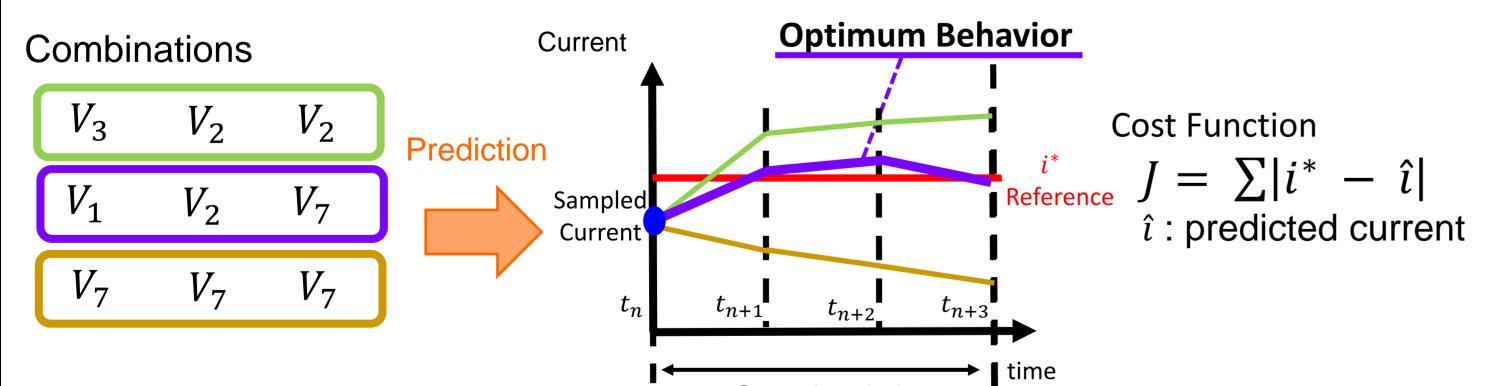
 $v_{amp} = K * (i^* - i)$ K: Gain

Voltage vector of Inverter

 $(V_0 \sim V_7)$

<u>MPC</u> -

Controller predicts <u>the future current behaviors</u> for vector combinations and <u>selects optimum input voltage</u> which cost function is minimum



Distribution is unimodal

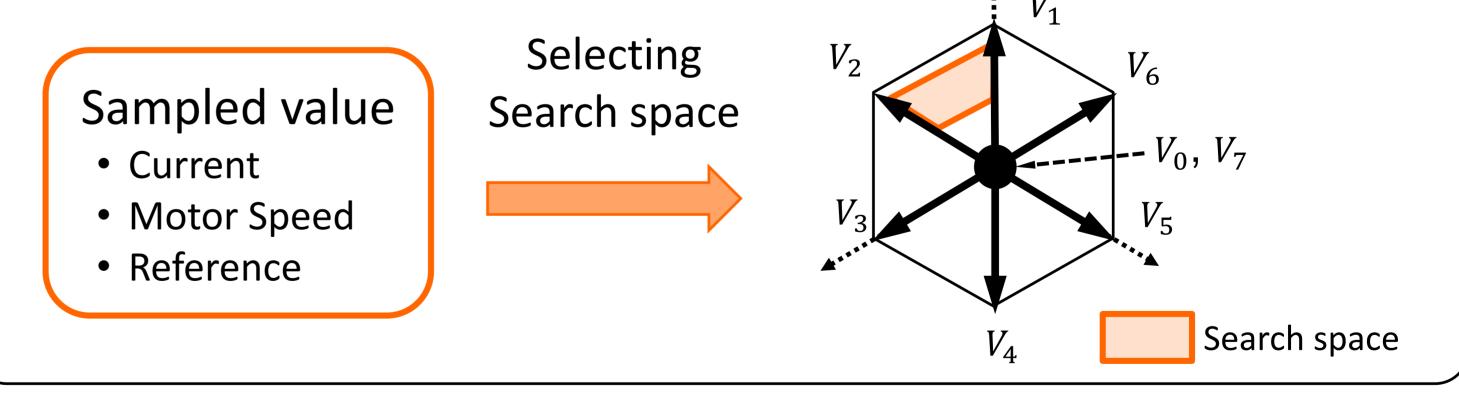
Controller can search optimum combination from the orange circle

Search space can be restrictable

Computational amount decreases due to space limitation

Propose limitation method for MPC

I have proposed the method to **limit the search space** by sensed driving situation



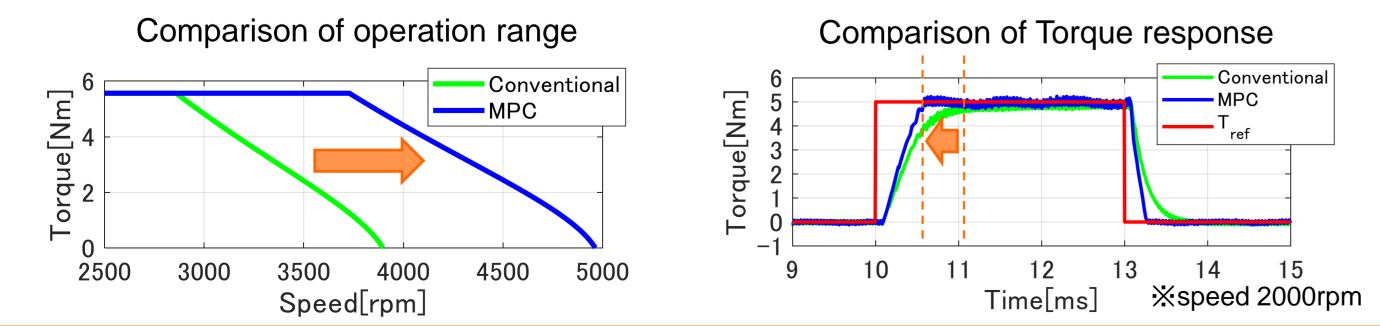
Comparison in same condition

Before space limit After space limit

Control period

Optimum Control by prediction and evaluation

Simulation Results



MPC is effective for wider operation range and Faster response

Simulation time	13.4h	24min
rate	100%	2.97%

Calculation time decrease by limiting the search space

Feasibility of MPC is improved

Future Plans of Doctoral dissertation

- Implementation of MPC for actual system
- Generalization of this method for other motors



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